PARALLEL-PLATE WAVEGUIDES

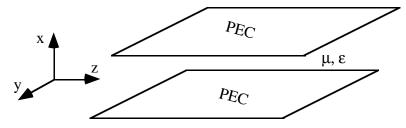
Wave Equation

$$\nabla^2 \mathbf{E} + \omega^2 \mu \varepsilon \mathbf{E} = \mathbf{0} \tag{1}$$

$$\frac{\partial^2 E_x}{\partial x^2} + \frac{\partial^2 E_x}{\partial y^2} + \frac{\partial^2 E_x}{\partial z^2} = -\omega^2 \mu \varepsilon E_x$$
(2a)

$$\frac{\partial^2 E_y}{\partial x^2} + \frac{\partial^2 E_y}{\partial y^2} + \frac{\partial^2 E_y}{\partial z^2} = -\omega^2 \mu \epsilon E_y$$
(2b)

$$\frac{\partial^2 E_z}{\partial x^2} + \frac{\partial^2 E_z}{\partial y^2} + \frac{\partial^2 E_z}{\partial z^2} = -\omega^2 \mu \epsilon E_z$$
(2c)



Transverse Electric (TE) Modes

For a parallel-plate waveguide, the plates are infinite in the y-extent; we need to study the propagation in the z-direction. The following assumptions are made in the wave equation

$$\Rightarrow \frac{\partial}{\partial y} = 0, \text{ but } \frac{\partial}{\partial x} \neq 0 \text{ and } \frac{\partial}{\partial z} \neq 0$$
$$\Rightarrow \text{Assume } E_y \text{ only}$$

These two conditions define the *TE modes* and the wave equation is simplified to read

$$\frac{\partial^2 E_y}{\partial x^2} + \frac{\partial^2 E_y}{\partial z^2} = -\omega^2 \mu \epsilon E_y$$
(3)

General solution (forward traveling wave)

$$E_{y}(x,z) = e^{-j\beta_{z}z} \left[Ae^{-j\beta_{x}x} + Be^{+j\beta_{x}x} \right]$$
(4)

At x = 0, $E_y = 0$ which leads to A + B = 0. Therefore, $A = -B = E_0/2j$, where E_0 is an arbitrary constant

At x = a, $E_y(x, z) = 0$. Let a be the distance separating the two PEC plates

$$E_{o}e^{-j\beta_{z}z}\sin\beta_{x}a = 0$$
(6)

This leads to :

$$\beta_{\rm x}a = m\pi$$
, where m = 1, 2, 3, ... (7)

or

$$\beta_{\rm X} = \frac{{\rm m}\pi}{{\rm a}} \tag{8}$$

Moreover, from the differential equation (3), we get the dispersion relation

$$\beta_z^2 + \beta_x^2 = \omega^2 \mu \varepsilon = \beta^2, \tag{9}$$

which leads to

$$\beta_{z} = \sqrt{\omega^{2} \mu \varepsilon - \left(\frac{m\pi}{a}\right)^{2}}$$
(10)

where m = 1, 2, 3, ... Since propagation is to take place in the z direction, for the wave to propagate, we must have $\beta_z^2 > 0$, or

$$\omega^2 \mu \varepsilon > \left(\frac{m\pi}{a}\right)^2 \tag{11}$$

This leads to the following guidance condition which will insure wave propagation

$$f > \frac{m}{2a\sqrt{\mu\varepsilon}}$$
 (12)

The *cutoff frequency* f_c is defined to be at the onset of propagation

$$f_{c} = \frac{m}{2a\sqrt{\mu\epsilon}}$$
(13)

The cutoff frequency is the frequency below which the mode associated with the index m will not propagate in the waveguide. Different modes will have different cutoff frequencies. The cutoff frequency of a mode is associated with the cutoff wavelength λ_c

$$\lambda_{\rm c} = \frac{\rm v}{\rm f_{\rm c}} = \frac{2\rm a}{\rm m} \tag{14}$$

Each mode is referred to as the TE_m mode (or $TE_{m,0}$ in Rao's book). From (6), it is obvious that there is no TE_0 mode and the first TE mode is the TE_1 mode.

Magnetic Field

From
$$\nabla \times \mathbf{E} = -j\omega\mu\mathbf{H}$$
 (15)

we have

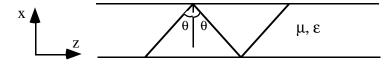
$$\mathbf{H} = \frac{-1}{j\omega\mu} \begin{vmatrix} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ \frac{\partial}{\partial x} & 0 & \frac{\partial}{\partial z} \\ 0 & \mathbf{E}_{y} & 0 \end{vmatrix}$$
(16)

which leads to

$$H_{x} = -\frac{\beta_{z}}{\omega\mu} E_{o} e^{-j\beta_{z}z} \sin\beta_{x}x$$
(17)

$$H_{z} = +\frac{j\beta_{x}}{\omega\mu}E_{o}e^{-j\beta_{z}z}\cos\beta_{x}x$$
(18)

As can be seen, there is no H_y component, therefore, the TE solution has E_y , H_x and H_z only.



From the dispersion relation, it can be shown that the propagation vector components satisfy the relations

$$\beta_{\rm Z} = \beta \sin\theta, \, \beta_{\rm X} = \beta \cos\theta \tag{19}$$

where θ is the angle of incidence of the propagation vector with the normal to the conductor plates.

Transverse Magnetic (TM) modes

The magnetic field also satisfies the wave equation:

$$\nabla^2 \mathbf{H} + \omega^2 \mu \varepsilon \mathbf{H} = \mathbf{0} \tag{20}$$

$$\frac{\partial^2 H_x}{\partial x^2} + \frac{\partial^2 H_x}{\partial y^2} + \frac{\partial^2 H_x}{\partial z^2} = -\omega^2 \mu \epsilon H_x$$
(21a)

$$\frac{\partial^2 H_y}{\partial x^2} + \frac{\partial^2 H_y}{\partial y^2} + \frac{\partial^2 H_y}{\partial z^2} = -\omega^2 \mu \epsilon H_y$$
(21b)

$$\frac{\partial^2 H_z}{\partial x^2} + \frac{\partial^2 H_z}{\partial y^2} + \frac{\partial^2 H_z}{\partial z^2} = -\omega^2 \mu \epsilon H_z$$
(21c)

For TM modes, we assume

$$\Rightarrow \frac{\partial}{\partial y} = 0, \text{ but } \frac{\partial}{\partial x} \neq 0 \text{ and } \frac{\partial}{\partial z} \neq 0$$
$$\Rightarrow \text{Assume H}_y \text{ only}$$

These two conditions define the TM modes and equations (21) are simplified to read

$$\frac{\partial^2 H_y}{\partial x^2} + \frac{\partial^2 H_y}{\partial z^2} = -\omega^2 \mu \epsilon H_y$$
(22)

General solution (forward traveling wave)

$$H_{y}(x,z) = e^{-j\beta_{z}z} \left[Ae^{-j\beta_{x}x} + Be^{+j\beta_{x}x} \right]$$
(23)

From
$$\nabla \times \mathbf{H} = \mathbf{j}\omega \mathbf{\epsilon} \mathbf{E}$$
 (24)

we get

$$\mathbf{E} = \frac{1}{\mathbf{j}\omega\varepsilon} \begin{vmatrix} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ \frac{\partial}{\partial \mathbf{x}} & 0 & \frac{\partial}{\partial \mathbf{z}} \\ 0 & \mathbf{H}_{\mathbf{y}} & 0 \end{vmatrix}$$
(25)

This leads to

$$E_{x}(x,z) = \frac{\beta_{z}}{\omega \varepsilon} e^{-j\beta_{z}z} \Big[A e^{-j\beta_{x}x} + B e^{+j\beta_{x}x} \Big]$$
(26)

$$E_{z}(x,z) = \frac{\beta_{x}}{\omega\varepsilon} e^{-j\beta_{z}z} \left[-Ae^{-j\beta_{x}x} + Be^{+j\beta_{x}x} \right]$$
(27)

At x=0, $E_z = 0$ which leads to $A = B = H_0/2$ where H_0 is an arbitrary constant. This leads to

$$H_{y}(x,z) = H_{o}e^{-j\beta_{z}z}\cos\beta_{x}x$$
(28)

$$E_{x}(x,z) = \frac{\beta_{z}}{\omega \varepsilon} H_{o} e^{-j\beta_{z}z} \cos\beta_{x} x$$
(29)

$$E_{z}(x,z) = \frac{j\beta_{x}}{\omega\varepsilon} H_{o} e^{-j\beta_{z}z} \sin\beta_{x}x$$
(30)

At x = a, $E_z = 0$ which leads to

$$\beta_x a = m\pi$$
, where m = 0, 1, 2, 3, ... (31)

This defines the TM modes which have only H_y , E_x and E_z components.

NOTE: THE DISPERSION RELATION, GUIDANCE CONDITION AND CUTOFF EQUA-TIONS FOR A PARALLEL-PLATE WAVEGUIDE ARE THE SAME FOR TE AND TM MODES.

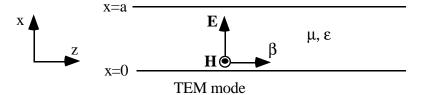
Equation (31) defines the TM modes; each mode is referred to as the TM_m mode (or $TM_{m,0}$ in Rao's book). It can be seen from (28) that m=0 is a valid choice; it is called the TM_0 , or *transverse electromagnetic* or TEM mode. For this mode $\beta_x=0$ and,

$$H_{v} = H_{o} e^{-j\beta_{z}z}$$
(32)

$$E_{x} = \frac{\beta_{z}}{\omega\epsilon} H_{o} e^{-j\beta_{z}z} = \sqrt{\frac{\mu}{\epsilon}} H_{o} e^{-j\beta_{z}z}$$
(33)

$$\mathbf{E}_{\mathbf{z}} = \mathbf{0} \tag{34}$$

where $\beta_z = \beta$, and in which there are no x variations of the fields within the waveguide. The TEM mode has a cutoff frequency at DC and is always present in the waveguide.



Time-Average Poynting Vector

TE modes

$$\langle \mathbf{P} \rangle = \frac{1}{2} \operatorname{Re} \{ \mathbf{E} \times \mathbf{H}^* \}$$
(35)

$$\langle \mathbf{P} \rangle = \frac{1}{2} \operatorname{Re} \left\{ \hat{\mathbf{y}} \mathbf{E}_{\mathbf{y}} \times \left[\hat{\mathbf{x}} \mathbf{H}_{\mathbf{x}}^* + \hat{\mathbf{z}} \mathbf{H}_{\mathbf{z}}^* \right] \right\}$$
(36)

$$\langle \mathbf{P} \rangle = \frac{1}{2} \operatorname{Re} \left\{ \hat{\mathbf{z}} \frac{\left| \mathbf{E}_{o} \right|^{2}}{\omega \mu} \beta_{z} \sin^{2} \beta_{x} x + \hat{\mathbf{x}} j \frac{\left| \mathbf{E}_{o} \right|^{2}}{\omega \mu} \beta_{x} \cos \beta_{x} x \sin \beta_{x} x \right\}$$
(37)

$$\langle \mathbf{P} \rangle = \hat{\mathbf{z}} \frac{\left| \mathbf{E}_{o} \right|^{2}}{\omega \mu} \beta_{z} \sin^{2} \beta_{x} x$$
(38)

TM modes

$$\langle \mathbf{P} \rangle = \frac{1}{2} \operatorname{Re} \{ \mathbf{E} \times \mathbf{H}^* \}$$
(39)

$$\langle \mathbf{P} \rangle = \frac{1}{2} \operatorname{Re} \left\{ \left[\hat{\mathbf{x}} \mathbf{E}_{\mathrm{x}} + \hat{\mathbf{z}} \mathbf{E}_{\mathrm{z}} \right] \times \hat{\mathbf{y}} \mathbf{H}_{\mathrm{y}}^{*} \right\}$$
(40)

$$\langle \mathbf{P} \rangle = \frac{1}{2} \operatorname{Re} \left\{ \hat{\mathbf{z}} \frac{\left|\mathbf{H}_{o}\right|^{2}}{\omega \varepsilon} \beta_{z} \cos^{2} \beta_{x} x - \hat{\mathbf{x}} j \frac{\left|\mathbf{H}_{o}\right|^{2}}{\omega \varepsilon} \beta_{x} \sin \beta_{x} x \cos \beta_{x} x \right\}$$
(41)

$$\langle \mathbf{P} \rangle = \hat{\mathbf{z}} \frac{\left|\mathbf{H}_{o}\right|^{2}}{\omega \varepsilon} \beta_{z} \cos^{2} \beta_{x} x$$
(42)

The total time-average power is found by integrating $\langle \mathbf{P} \rangle$ over the area of interest.